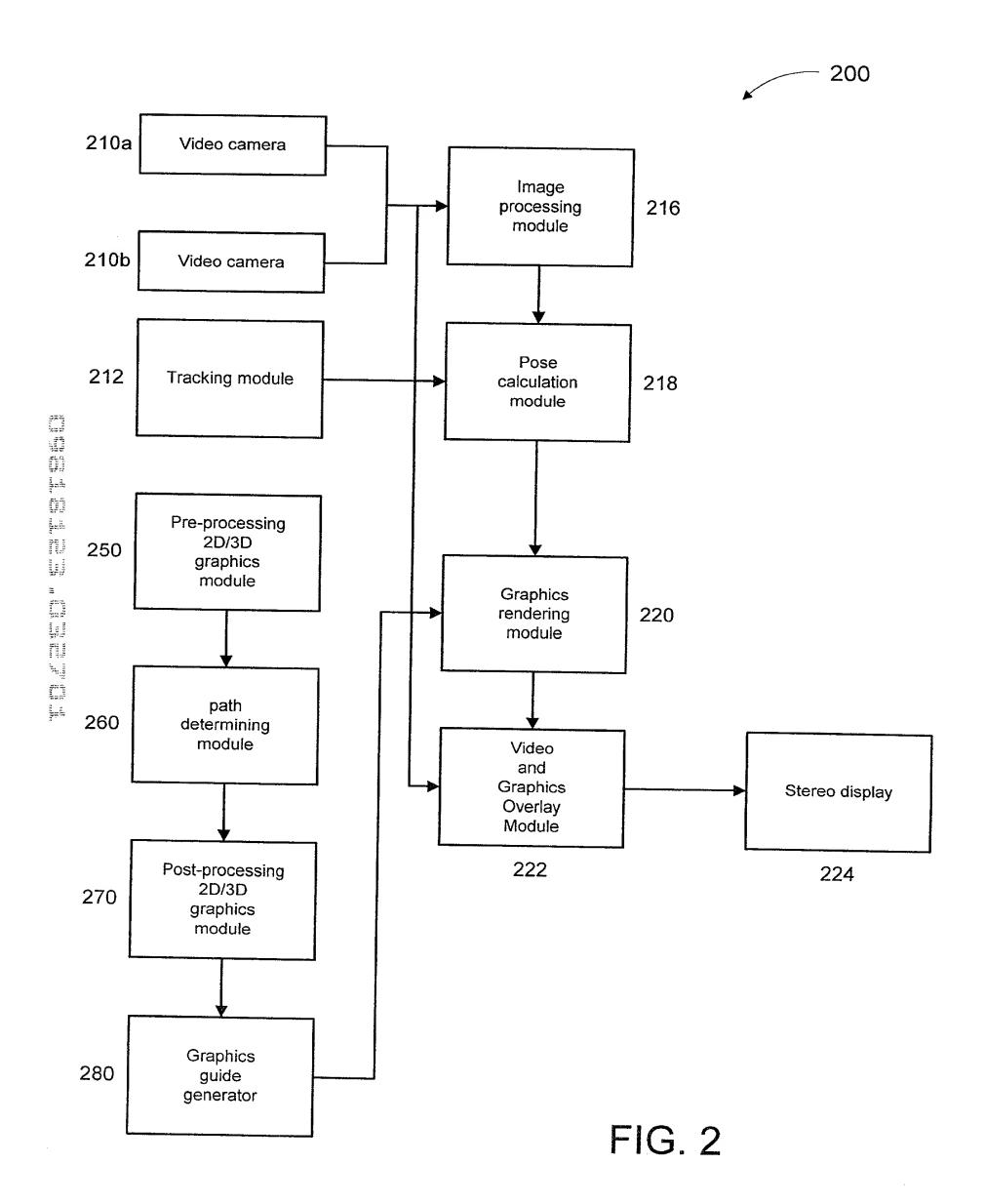
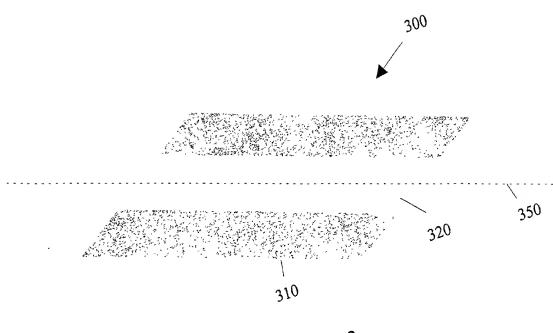


F16. 1







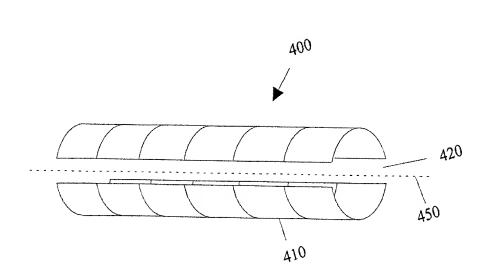
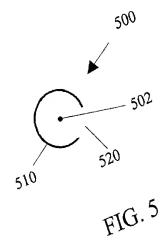
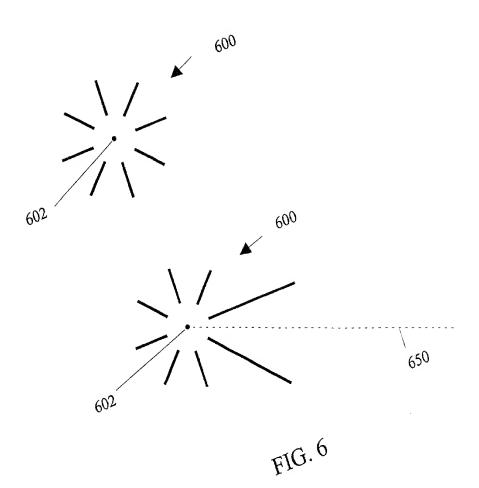
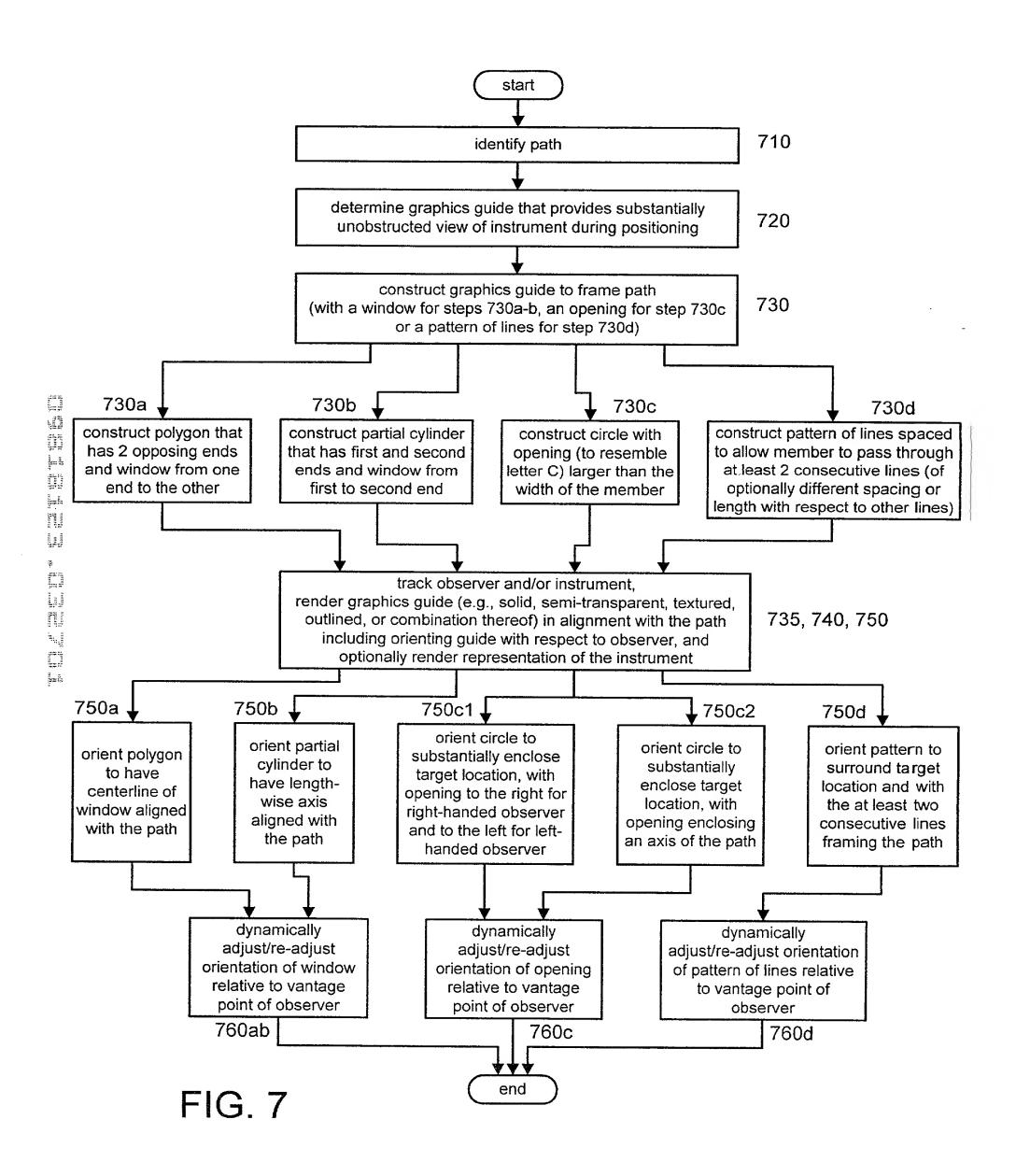


FIG. 4







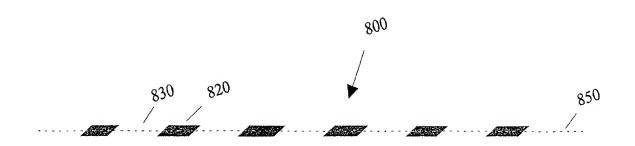


FIG. 8

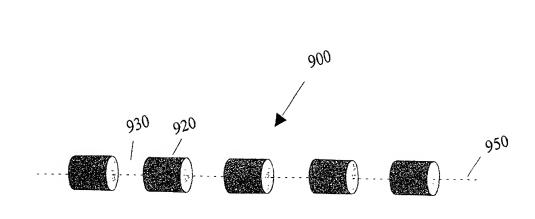


FIG.9

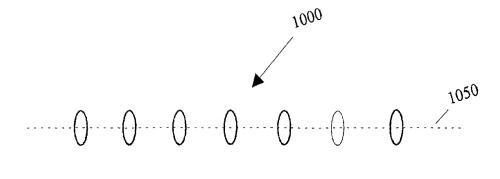


FIG. 10

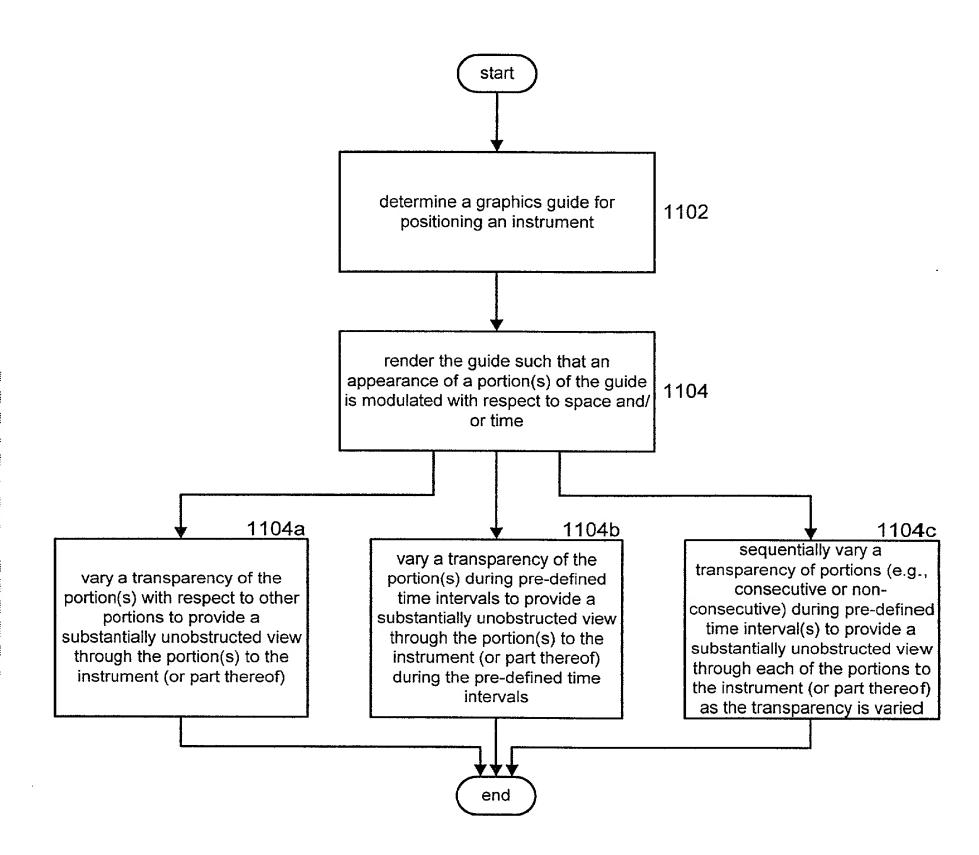


FIG. 11A

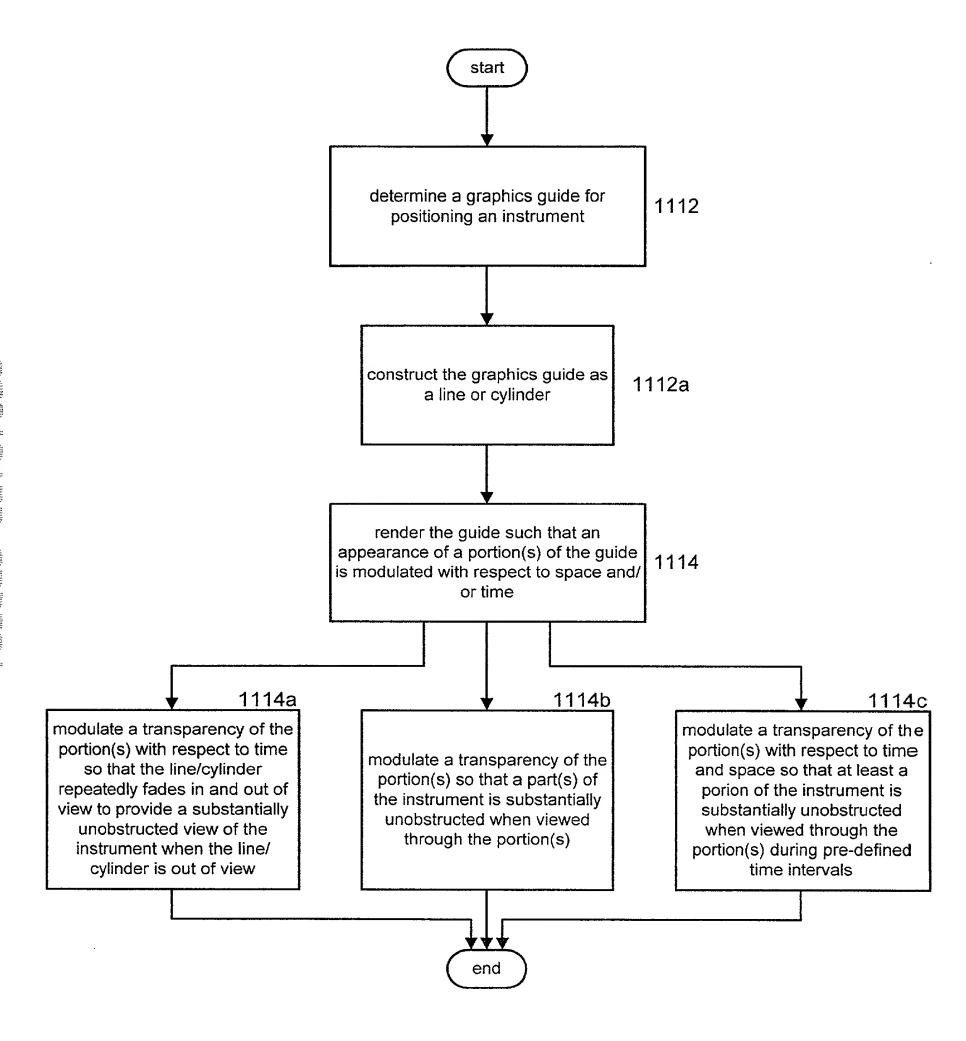


FIG. 11B

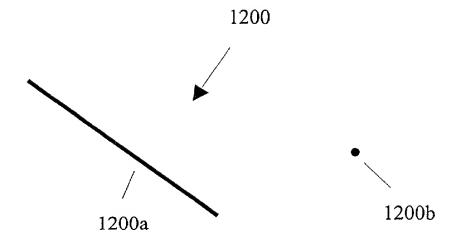


FIG. 12

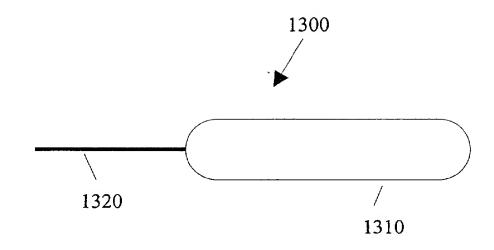
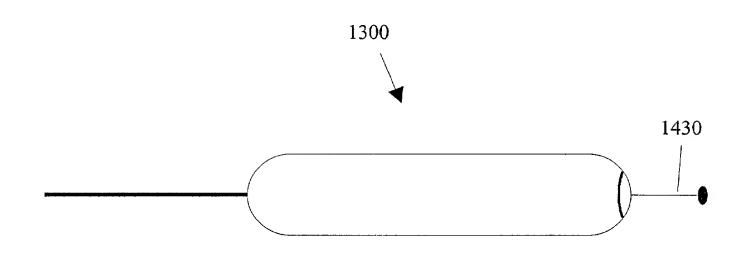


FIG. 13



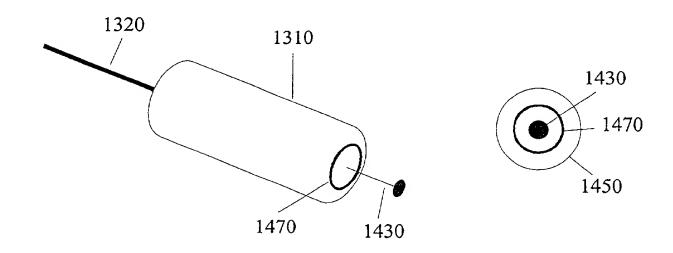
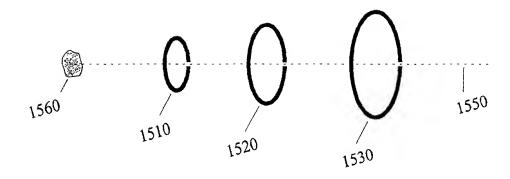
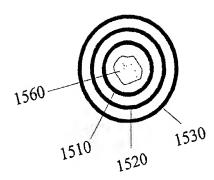


FIG. 14





The state of the s

FIG. 15

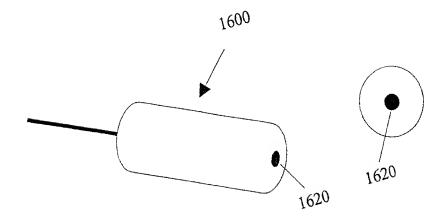
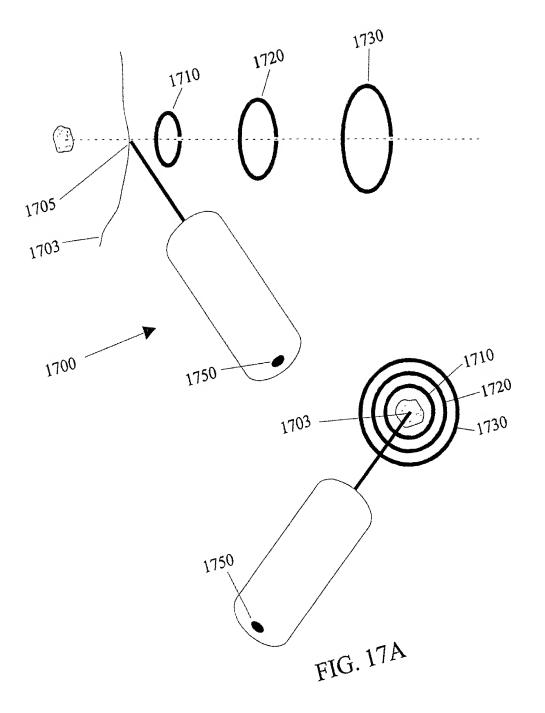


FIG. 16





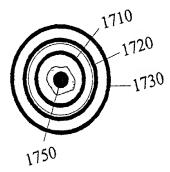


FIG. 17B

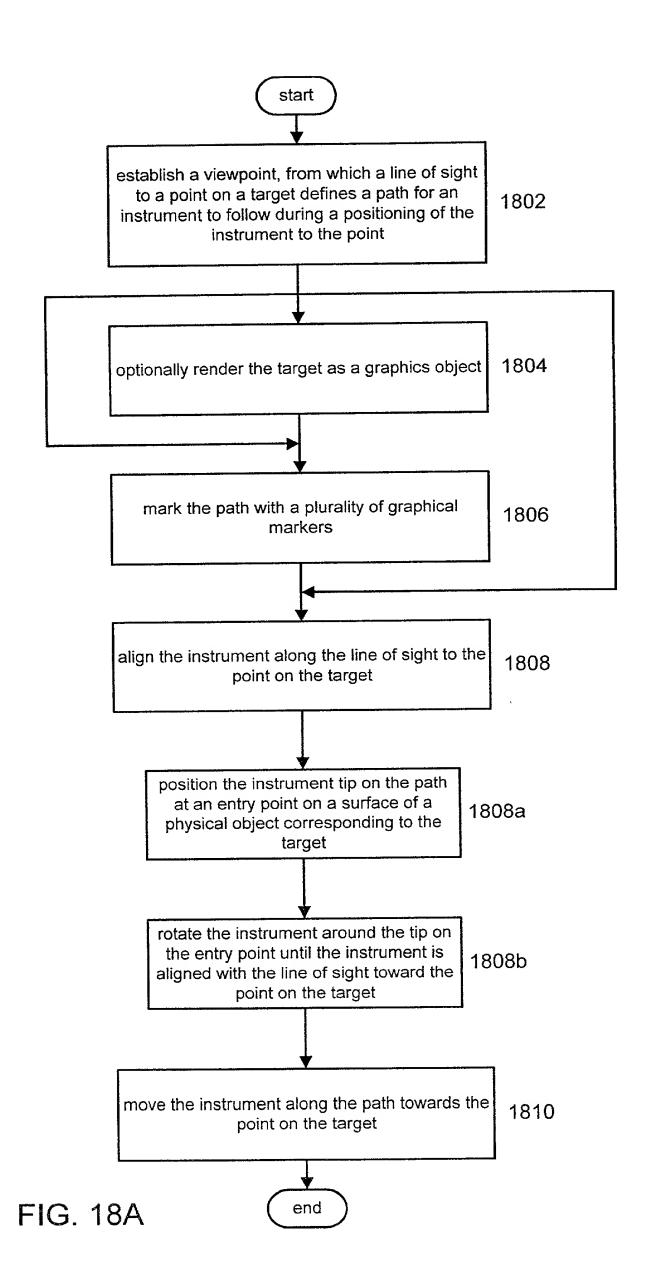
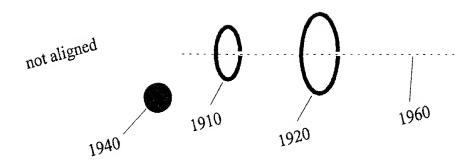


FIG. 18B



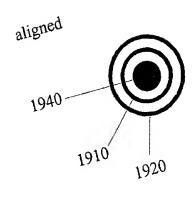
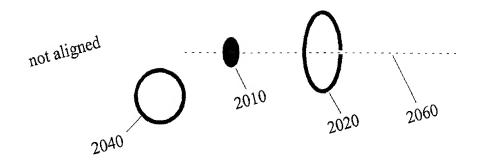
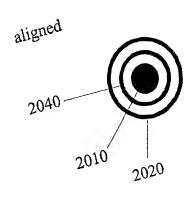


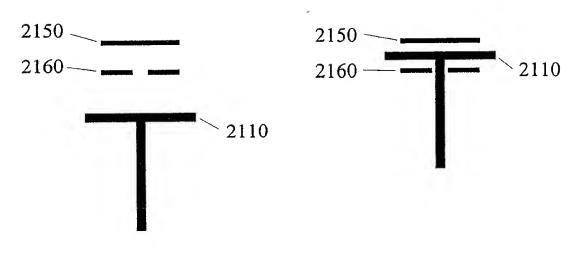
FIG. 19





The straight of the straight o

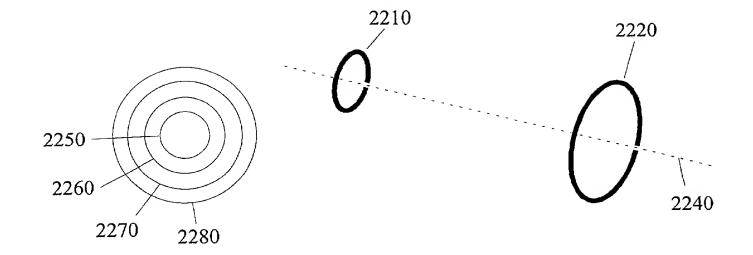
FIG. 20

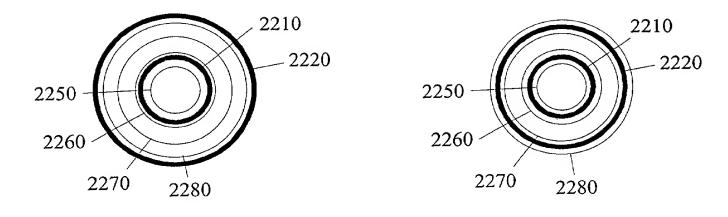


target depth not yet reached

taget depth reached

FIG. 21

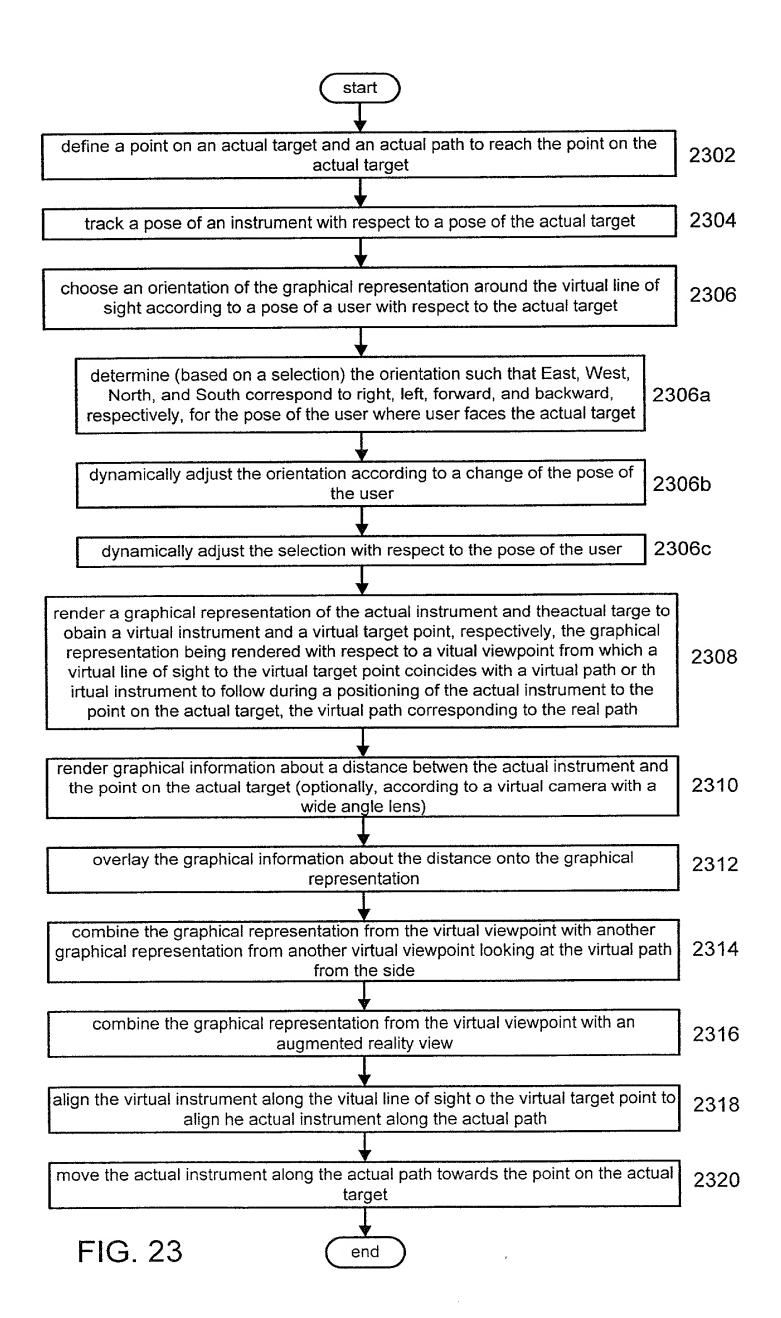




aligned with path, but not at correct depth

aligned with path, and at correct depth

FIG. 22



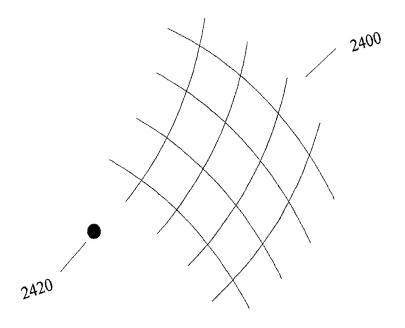
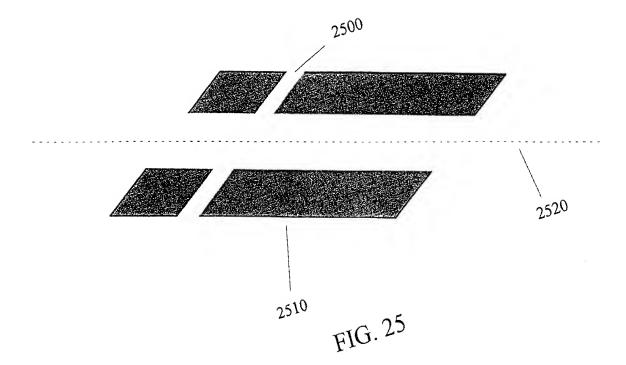


FIG. 24



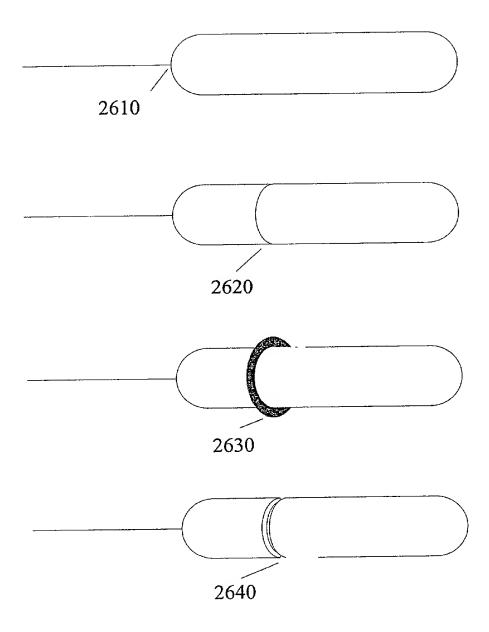


FIG. 26

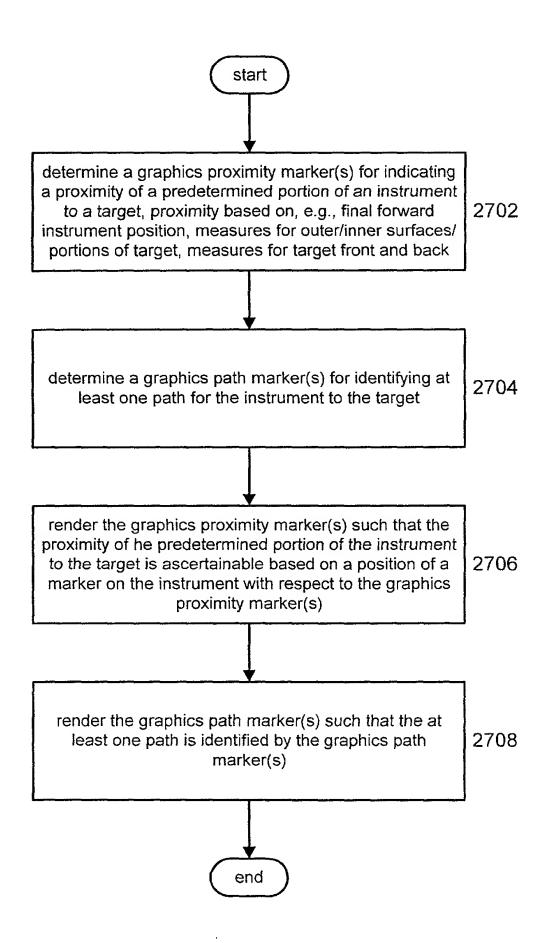


FIG. 27